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## On the Curvature Tensors of the Indicatrix Bundle over a Finsler Space

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**Introduction.** Let  $M$  be an  $n$ -dimensional Finsler space with a fundamental function  $F(x, y)$ , and let  $T(M)$  and  $T^*(M)$  be the tangent bundle and cotangent bundle over  $M$ . Now we consider a mapping

$$\Psi : (x, y) \in T(M) \rightarrow (x, p) \in T^*(M), \quad \text{where } p_i = \partial F / \partial y^i.$$

Then  $N = \Psi(T(M))$  is a hypersurface of  $T^*(M)$  and called the  $p$ -manifold of  $M$ , which was first introduced and studied by M. Kurita [4]<sup>1)</sup>.

Afterwards the  $p$ -manifold  $N$  was studied concretely and combined to the theory of A. Deicke ([1], [2]) by H. Yasuda ([8], [9]). The  $p$ -manifold  $N$  is in fact the *figuratrix bundle* over  $M$ . Hereafter we shall use this terminology and  $l_i$  instead of  $p_i$ . The figuratrix bundle was applied to a study of Finsler spaces with absolute parallelism of line-elements [10].

Similarly we can consider the *indicatrix bundle*  $L = \bigcup_{x \in M} I_x$  over  $M$ ,  $I_x$  being the indicatrix at a point  $x$  of  $M$ , and introduce a metric on  $L$  in a natural way. In this case,  $L$  is isometric to  $N$  by a mapping  $:(x^i, l^i) \in L \rightarrow (x^i, l_i) \in N$  defined by  $l_i = g_{ij} l^j$ , where  $l^j = y^j / F(x, y)$ . Therefore, we can use the methods constructed already in  $N$  for the studies of  $L$  itself and their applications.

Along the above statement, the indicatrices of  $M$  and curves in  $L$  were investigated in the papers [11] and [12] where  $L$  is endowed with the  $D$ -connection. Especially, the indicatrix bundle  $L$  endowed with the  $K$ -

1) Numbers in brackets refer to the references at the end of the paper.

connection was treated in the paper [13].

On the other hand, from a standpoint of the theory of Finsler bundle and tangent bundle the indicatrix bundle  $L$  over  $M$  is constructed systematically and studied by M. Matsumoto [6], and the metric and the connection introduced there correspond to our metric and the  $K$ -connection respectively.

In consideration of the  $D$ - and  $K$ -connections, Landsberg spaces are treated in the paper [14].

In the present paper, we shall reconstruct the indicatrix bundle  $L$  from a standpoint of the theory of implicit functions and differential forms and investigate the curvature tensors on  $L$  when  $L$  is endowed with the  $K_0$ -,  $D_0$ -,  $K$ - and  $D$ -connections. Especially, for the  $D_0$ - and  $D$ -connections we have found many new tensors on  $M$ . As for the geometrical meanings of these tensors, we have obtained the considerable results when  $M$  is a Landsberg space. However, the most part of our problem remains to be solved. The terminologies and notations are referred to the papers ([12], [13]) unless otherwise stated.

**§ 1. Construction of the indicatrix bundle.** The indicatrix bundle  $L$  in Introduction can be constructed over  $M$  globally. However, it is in fact enough to consider  $L$  at a coordinate neighborhood.

Let  $U$  be a coordinate neighborhood with coordinates  $(x^i)$  ( $i=1, 2, \dots, n$ ) of  $M$ . Then, if we denote by  $y=y^i \partial / \partial x^i$  an element of the tangent space  $T_x$  at a point  $x$  of  $M$ , the canonical coordinates of  $\bar{U} = \bigcup_{x \in U} T_x$  are expressed in  $(x^i, y^i)$ . The indicatrix bundle  $L$  is a hypersurface of  $T(M)$  and its local equation is given by

$$(1.1) \quad G = F(x, y) - 1 = 0.$$

On  $L$  we have from (1.1)

$$(1.2) \quad \partial G / \partial x^i = \gamma_{oi}^o, \quad \partial G / \partial y^i = l_i,$$

where  $\gamma_{k^j i}^j$  are the Christoffel symbols formed by the metric tensor  $g_{ij}$  and  $\gamma_{oi}^o = \gamma_{k^j i}^j l^k l_j$ . Since the vector  $l_i$  is presupposed as a non-zero one, we can assume  $\partial G / \partial y^n = l_n \neq 0$  without loss of generality. Therefore according to the theorem of implicit functions, there exists a neighborhood  $\tilde{U}$  such that the equation (1.1) can be solved as

$$(1.3) \quad y^n = y^n(x^1, x^2, \dots, x^n, y^1, y^2, \dots, y^{n-1})$$

and the following relations hold good in  $\widetilde{U}$  by virtue of (1.2):

$$(1.4) \quad \partial y^n / \partial x^i = -\gamma_{oi}^o / l_n, \quad \partial y^n / \partial y^\lambda = -l_\lambda / l_n (\lambda = 1, 2, \dots, n-1).$$

In this case, if we substitute (1.3) in (1.1), then the expression (1.1) becomes an identity and hence  $l^i = y^i / F = y^i$ . Therefore, for (1.3) and (1.4) we can rewrite as

$$(1.3)' \quad l^n = l^n(x^1, \dots, x^n, l^1, \dots, l^{n-1}),$$

$$(1.4)' \quad \partial l^n / \partial x^i = -\lambda_{oi}^o / l_n, \quad \partial l^n / \partial l^\lambda = -l_\lambda / l_n.$$

Now we denote by  $((\partial / \partial x^i)_L, (\partial / \partial l^\lambda)_L)$  the natural frame at a point  $(x^i, l^\lambda)$  of  $L$  and consider the inclusion mapping  $\iota: L \rightarrow T(M)$ .

For any homogeneous function  $f(x^i, y^i)$  of degree  $O$  in  $y^i$ , we have

$$(1.5) \quad (\partial / \partial l^i) f = F (\partial / \partial y^i) f \quad i. e. \quad \partial / \partial l^i = F \partial / \partial y^i.$$

Then it follows from (1.4)' and (1.5) that

$$(1.6) \quad \begin{aligned} \iota_* (\partial / \partial x^i)_L &= \partial / \partial x^i - (\gamma_{oi}^o / l_n) F \partial / \partial y^n, \\ \iota_* (\partial / \partial l^\lambda)_L &= F \partial / \partial y^\lambda - (l_\lambda / l_n) \partial / \partial y^n, \end{aligned}$$

where  $(\partial / \partial x^i, \partial / \partial y^i)$  is the natural frame at a point  $(x^i, y^i)$  of  $T(M)$ .

Remark. At the present stage, since  $F=1$  we have  $\partial / \partial y^i = \partial / \partial l^i$ . Especially when the vector  $\partial / \partial l^i$  operates to homogeneous objects of degree  $O$  in  $y^i$ , (1.5) is valid and it corresponds to the third covariant differentiation  $\parallel i$  of Cartan.

In this case, it is seen from (1.6) that the coframe  $(\iota^*(dx^i), \iota^*(dl^\lambda))$  is dual to  $((\partial / \partial x^i)_L, (\partial / \partial l^\lambda)_L)$ , and from (1.3)' and (1.4)' that

$$(1.7) \quad \iota^*(dl^n) = -(\gamma_{oi}^o / l_n) \iota^*(dx^i) - (l_\lambda / l_n) \iota^*(dl^\lambda).$$

In the sequel, we shall omit the symbols  $\iota_*$  and  $\iota^*$  when no confusion occurs.

Now, let us consider the Cartan connection  $\Gamma_{j^i k}^*$  on  $M$  and the non-



linear connection  $\Gamma^*_{\kappa^i_j} y^k$  on  $T(M)$ . Then, denoting by  $(\bar{e}_i)$  the horizontal lift of  $(\partial/\partial x^i)$  to  $T(M)$  with respect to this non-linear connection, we have

$$(1.8) \quad \bar{e}_i = \partial/\partial x^i - \Gamma^*_{\kappa^j_i} y^k \partial/\partial y^j .$$

Further, if we put

$$(1.9) \quad \bar{e}_{(i)} = \bar{e}_{n+i} = \partial/\partial y^i, \quad Dy^i = dy^i + \Gamma^*_{\kappa^i_j} y^k dx^j,$$

then it is seen from (1.8) and (1.9) that the coframe  $(dx^i, Dy^i)$  is dual to  $(\bar{e}_i, \bar{e}_{(i)})$ . Then, carrying the coframe  $(dx^i, Dy^i)$  back to  $L$  by  $\iota^*$ , from (1.7) and (1.9) we obtain the coframe  $(dx^i, Dl^i)$  on  $L$  and

$$(1.10) \quad \begin{aligned} Dl^\lambda &= dl^\lambda + N^\lambda_j dx^j, \\ Dl^n &= (N^n_i - \gamma^o_i/l_n) dx^i - (l_\lambda/l_n) dl^\lambda, \end{aligned}$$

where we put  $N^i_j = \Gamma^*_{\sigma^i_j} = \Gamma^*_{\kappa^i_j} l^k$ . Moreover if we denote by  $(e_i, e_{(\lambda)})_L$  the frame dual to  $(dx^i, Dl^\lambda)$ , we have

$$(1.11) \quad (e_i)_L = (\partial/\partial x^i)_L - N^\lambda_i (e_{(\lambda)})_L, \quad (e_{(\lambda)})_L = (\partial/\partial l^\lambda)_L.$$

Then it follows from (1.5), (1.6), (1.8), (1.9) and (1.11) that

$$(1.12) \quad \begin{aligned} (e_i)_L &= \partial/\partial x^i - N^j_i \partial/\partial l^j = \bar{e}_i, \\ (e_{(\lambda)})_L &= \partial/\partial l^\lambda - (l_\lambda/l_n) \partial/\partial l^n. \end{aligned}$$

In the following, we shall write  $(e_i)_L$  and  $(e_{(\lambda)})_L$  as  $e_i$  and  $e_{(\lambda)}$  simply.

A metric  $d\sigma^2$  on  $L$  is introduced in a natural way ([2], [9]) by

$$(1.13) \quad d\sigma^2 = g_{ij} dx^i dx^j + g_{(i)(j)} Dl^i Dl^j .$$

Now, let us find an orthonormal frame and coframe on  $L$  with respect to the above metric. For this purpose, we first choose  $n$  vector fields  $\xi^i_a$  ( $a=1, 2, \dots, n$ ) on  $M$  satisfying

$$(1.14) \quad \xi^i_n = l^i, \quad g_{ij} \xi^i_a \xi^j_b = \delta_{ab} .$$

And further if we denote by  $(\zeta^a)$  the inverse of the matrix  $(\xi^i_a)$ , then from (1.14) we have

$$(1.15) \quad g^{ij} = \sum_a \xi_a^i \xi_a^j, \quad g_{ij} = \sum_a \xi_a^i \xi_a^j, \quad l_i = \xi_i^n, \quad \xi_a^i = g^{ij} \xi_j^a, \\ \xi_a^i l_i = \xi_i^a l^i = 0 \quad (\alpha=1, 2, \dots, n-1),$$

where  $g^{ij}$  is the reciprocal tensor of  $g_{ij}$ . Put

$$(1.16) \quad e_a = \xi_a^i e_i, \quad e_{(\alpha)} = \xi_\alpha^i \partial / \partial l^i,$$

$$(1.17) \quad \omega^a = \xi_i^a dx^i, \quad \omega^{(\alpha)} = \xi_i^\alpha D l^i.$$

Then we can state

**Proposition 1.** *The frame  $(e_a, e_{(\alpha)})$  and coframe  $(\omega^a, \omega^{(\alpha)})$  formed by (1.16) and (1.17) are dual to each other. And they are an orthonormal frame and coframe with respect to the metric defined by (1.13).*

*Proof.* We know already that  $(e_i, e_{(\lambda)})$  and  $(dx^i, D l^\lambda)$  are dual to each other. So we have

$$(1.18) \quad dx^i(e_j) = \delta_j^i, \quad dx^i(e_{(\lambda)}) = D l^\lambda(e_j) = 0, \quad D l^\lambda(e_{(\mu)}) = \delta_\mu^\lambda.$$

From (1.12) we get

$$(1.19) \quad e_{(\alpha)} = \xi_\alpha^\lambda e_{(\lambda)}.$$

If we put  $\eta_\alpha^\lambda = \xi_\alpha^\lambda - (l_\lambda/l_\alpha) \xi_\alpha^\alpha$ , then we obtain

$$(1.20) \quad \xi_\beta^\lambda \eta_\alpha^\lambda = \delta_\beta^\alpha, \quad \omega^{(\alpha)} = \eta_\alpha^\lambda D l^\lambda.$$

Thus on making use of (1.16)~(1.20), we have

$$(1.21) \quad \omega^a(e_b) = \delta_b^a, \quad \omega^a(e_{(\alpha)}) = \omega^{(\alpha)}(e_a) = 0, \\ \omega^{(\alpha)}(e_{(\beta)}) = \delta_\beta^\alpha.$$

Next, it follows from (1.13), (1.15) and (1.17) that

$$(1.22) \quad \sum_a \omega^a \omega^a = g_{ij} dx^i dx^j, \quad \sum_\alpha \omega^{(\alpha)} \omega^{(\alpha)} = g_{ij} D l^i D l^j, \\ d\sigma^2 = \sum_a \omega^a \omega^a + \sum_\alpha \omega^{(\alpha)} \omega^{(\alpha)},$$

that is, the coframe  $(\omega^a, \omega^{(\alpha)})$  is an orthonormal one with respect to the metric and so is the frame  $(e_a, e_{(\alpha)})$ . Q. E. D.

A frame and coframe introduced in proposition 1 are usually called

an adapted orthogonal frame and coframe respectively. And it follows from (1.22) that the components of the metric tensor with respect to  $(e_a, e_{(a)})$  are given by  $\delta_{AB}$  ( $A, B = 1, 2, \dots, 2n-1$ ).

If we put  $e_{(i)} = \xi_i^\alpha e_{(\alpha)}$ , from (1.16) we have

$$(1.23) \quad e_{(i)} = h_i^j \partial / \partial l^j, \quad \text{where } h_i^j = \delta_i^j - l^j l_i,$$

In this case, the frame  $(e_i, e_{(i)})$  is considered also as a frame on  $L$ , but it should be noticed that  $(e_{(i)})$  are not independent because of  $l^i e_{(i)} = 0$ .

§ 2. Connections and torsion tensors. Though the choice of metrical connectons on  $L$  with respect to the metric (1.13) is highly arbitrary, in this paper we shall consider the four connections, that is,  $K_0$ -,  $K$ -,  $D_0$ -  $D$ -connections. Hereafter we take an adapted orthogonal coframe  $(\omega^a, \omega^{(a)})$ .

Let  $\omega_B^A$  be the connection forms with respect to  $(\omega^a, \omega^{(a)})$  of a connection  $\Gamma$  on  $L$ . Since  $D\delta_{AB} = -\omega_A^B - \omega_B^A$ , any metrical connection  $\Gamma$  is given by

$$(2.1) \quad \Gamma = (\omega_B^A), \quad \omega_B^A = -\omega_A^B.$$

Firstly, the  $K_0$ -connection is defined as follows: In (2.1),

$$(2.2) \quad \omega_{(\beta)}^{(\alpha)} = \omega_{\beta}^{\alpha}, \quad \omega_n^{\alpha} = \omega_{(\beta)}^{\alpha} = \omega_b^{\alpha} = \omega_b^{(\beta)} = 0, \quad \omega_{\beta}^{\alpha} = \Gamma_{\beta c}^{\alpha} \omega^c + \Gamma_{\beta(\gamma)}^{\alpha} \omega^{(\gamma)},$$

$$\Gamma_{\beta c}^{\alpha} = -\xi_{i|\beta}^{\alpha} \xi_b^i \xi_c^j, \quad \Gamma_{\beta(\gamma)}^{\alpha} = -\xi_i^{\alpha} |_{\beta} \xi_b^i \xi_{\gamma}^j.$$

Secondly, the  $K$ -connection is defined as follows: In (2.1),

$$(2.3) \quad \omega_b^a = \Gamma_{bc}^a \omega^c + \Gamma_{b(\gamma)}^a \omega^{(\gamma)}, \quad \omega_{(\beta)}^{(\alpha)} = \omega_{\beta}^{\alpha}, \quad \omega_{(\beta)}^a = \omega_b^{(\beta)} = 0,$$

$$\Gamma_{bc}^a = -\xi_{i|bc}^a \xi_b^i \xi_c^j, \quad \Gamma_{b(\gamma)}^a = -\xi_i^a |_{\beta} \xi_b^i \xi_{\gamma}^j.$$

Thirdly, the  $D$ -connection is defined as follows: In (2.1),  $\omega_b^a$  and  $\omega_{(\beta)}^{(\alpha)}$  are the same as in (2.3),  $-\omega_{(\alpha)}^{(\beta)} = \omega_{(\alpha)}^{\beta} = \Gamma_{b(\alpha)}^{\beta} \omega^c + \Gamma_{b(\gamma)}^{(\beta)} \omega^{(\gamma)}$  and

$$(2.4) \quad \Gamma_{b(\alpha)}^{(\beta)} = B^i{}_{jk} \xi_i^{\alpha} \xi_b^j \xi_c^k, \quad \Gamma_{b(\gamma)}^{(\alpha)} = P^i{}_{jk} \xi_i^{\alpha} \xi_b^j \xi_{\gamma}^k,$$

$$B^i{}_{jk} = A^i{}_{jk} + R^i{}_{jk}, \quad P^i{}_{jk} = P_o^i{}_{jk} = A^i{}_{j\kappa} \omega_{\kappa}, \quad R^i{}_{jk} = R_o^i{}_{jk}.$$



Lastly, the  $D_o$ -connection is defined as follows: In (2.1), the forms  $\omega_\beta^a$ ,  $\omega_{\beta}^{(\alpha)}$ ,  $\omega_n^a$  and  $\omega_b^n$  are the same as in (2.2), while  $\omega_b^{(\alpha)}$  and  $\omega_{\alpha}^b$  are the same as in (2.4).

The torsion form  $\tau^A$  and tensor  $T_{BC}^A$  on  $L$  are given by

$$(2.5) \quad \tau^A = d\omega^A - \omega^B \wedge \omega_B^A = \frac{1}{2} T_{BC}^A \omega^B \wedge \omega^C \quad (T_{BC}^A + T_{CB}^A = 0).$$

For the  $D$ -connection, from (1.17) and (2.4) we have [9]

$$(2.6) \quad \begin{aligned} T_{bc}^a &= T_{(\beta)(\gamma)}^{\alpha} = T_{(\beta)c}^{\alpha} = 0, \quad T_{(\beta)c}^a = -T_{c(\beta)}^a = -R_{ijk} \xi_i^a \xi_b^j \xi_c^k \\ T_b^{(\alpha)c} &= -T_{(\alpha)c}^b = R_{ijk} \xi_i^a \xi_b^j \xi_c^k, \quad R_{ijk} = g_{ih} R^h{}_{jk}, \end{aligned}$$

from which it follows that  $T_{BC}^A = 0$  if and only if  $R^i{}_{jk} = 0$ , and that  $T_{BC}^A$  are skew-symmetric in all indices  $A, B$  and  $C$ , that is, a path in  $L$  coincides with an extremal in  $L$  [2]. Accordingly we have

**Proposition 2.** *The  $D$ -connection is the Riemannian one if and only if  $M$  is a space with absolute parallelism of line-elements. With respect to the  $D$ -connection, a path in  $L$  coincides with an extremal in  $L$ .*

For the  $K$ -connection, from (1.17) and (2.3) we have ([6], [9], [13])

$$(2.7) \quad \begin{aligned} T_{bc}^a &= T_{(\beta)(\gamma)}^{\alpha} = T_{(\beta)c}^{\alpha} = 0, \quad T_{(\gamma)b}^a = -T_{b(\gamma)}^a = A_{jk}^i \xi_i^a \xi_b^j \xi_c^k, \\ T_b^{(\alpha)c} &= -T_c^{(\alpha)b} = R_{ijk}^a \xi_i^a \xi_b^j \xi_c^k, \quad T_{b(\gamma)}^{\alpha} = -T_{(\gamma)b}^{\alpha} = P_{jk}^i \xi_i^a \xi_b^j \xi_c^k, \end{aligned}$$

For the  $K_o$ -connection, from (1.17) and (2.2) we have [9]

$$(2.8) \quad \begin{aligned} T_{bc}^a &= T_{(\beta)(\gamma)}^{\alpha} = T_{(\beta)c}^{\alpha} = 0, \quad T_{(\gamma)b}^a = -T_{b(\gamma)}^a \\ &= (A_{jk}^i + l_j h_k^i + l_k h_j^i) \xi_i^a \xi_b^j \xi_c^k, \\ T_b^{(\alpha)c} &= -T_c^{(\alpha)b} = R_{ijk}^a \xi_i^a \xi_b^j \xi_c^k, \quad T_{b(\gamma)}^{\alpha} = -T_{(\gamma)b}^{\alpha} = P_{jk}^i \xi_i^a \xi_b^j \xi_c^k. \end{aligned}$$

Assume  $T_{b(\gamma)}^a = 0$ . Then from (2.8) we obtain  $A_{jk}^i + l_j h_k^i + l_k h_j^i = 0$ , contraction of which by  $l^k$  yields  $h_j^i = 0$ , contrary to hypothesis.

For the  $D_o$ -connection, from (1.17), (2.2) and (2.4) we have

$$(2.9) \quad T_{bc}^a = T_{(\beta)(\gamma)}^{\alpha} = T_{(\beta)c}^{\alpha} = 0, \quad T_b^{(\alpha)c} = -T_c^{(\alpha)b} = R_{ijk}^a \xi_i^a \xi_b^j \xi_c^k,$$

$$T_{(\beta)c}^a = -T_{c(\beta)}^a = (l_j h_{ik} + l_i h_{jk} - R_{kij}) \xi_i^i \xi_c^j \xi_\beta^k.$$

Assume  $T_{BC}^A = 0$ . Then in the same way as before we have  $h_{jk} = 0$ . Thus by virtue of (2.7) and the above proofs we can state

**Proposition 3.** *The K-connection is symmetric if and only if M is locally Euclidean. For either of the  $K_o$ - and  $D_o$ -connections, the torsion tensor  $T_{BC}^A$  never vanishes.*

§ 3. Curvature tensors. Let  $\mathcal{Q}_B^A$  and  $K_{BCD}^A$  be the curvature form and tensor on L. Then they are defined by ([9], [13])

$$(3.1) \quad \mathcal{Q}_B^A = \omega_B^c \wedge \omega_c^A - d\omega_B^A = \frac{1}{2} K_{BCD}^A \omega^c \wedge \omega^D \quad (K_{BCD}^A = -K_{BDC}^A),$$

which is reducible to

$$(3.2) \quad \mathcal{Q}_B^A = \frac{1}{2} R_{BCd}^A \omega^c \wedge \omega^d + P_{BC(\sigma)}^A \omega^c \wedge \omega^{(\sigma)} + \frac{1}{2} S_{B^{(\gamma)(\sigma)}}^A \omega^{(\gamma)} \wedge \omega^{(\sigma)}.$$

First, for the K-connection we know ([9], [13]) that

$$(3.3) \quad \begin{aligned} \mathcal{Q}_b^a &= \omega_b^c \wedge \omega_c^a - d\omega_b^a = \frac{1}{2} R_{bcd}^a \omega^c \wedge \omega^d + P_{bc(\sigma)}^a \omega^c \wedge \omega^{(\sigma)} \\ &\quad + \frac{1}{2} S_{b^{(\gamma)(\sigma)}}^a \omega^{(\gamma)} \wedge \omega^{(\sigma)}, \\ R_{bcd}^a &= R_{jkh}^i \xi_i^a \xi_b^j \xi_c^k \xi_d^h, \quad P_{bc(\sigma)}^a = P_{jkh}^i \xi_i^a \xi_b^j \xi_c^k \xi_\sigma^h, \\ S_{b^{(\gamma)(\sigma)}}^a &= S_{jkh}^i \xi_i^a \xi_b^j \xi_\gamma^k \xi_\sigma^h, \end{aligned}$$

where  $R_{jkh}^i$ ,  $P_{jkh}^i$  and  $S_{jkh}^i$  are the  $h$ -,  $hv$ -,  $v$ -curvature tensors on M.

Next, for the  $K_o$ -connection we know [9] that

$$(3.4) \quad \begin{aligned} \mathcal{Q}_{(\beta)}^{\alpha} &= \mathcal{Q}_\beta^\alpha = \omega_\beta^\gamma \wedge \omega_\gamma^\alpha - d\omega_\beta^\alpha = \frac{1}{2} R_{\beta cd}^\alpha \omega^c \wedge \omega^d \\ &\quad + P_{\beta c(\sigma)}^\alpha \omega^c \wedge \omega^{(\sigma)} + \frac{1}{2} S_{\beta^{(\gamma)(\sigma)}}^\alpha \omega^{(\gamma)} \wedge \omega^{(\sigma)}, \\ R_{(\beta)cd}^\alpha &= R_{\beta cd}^\alpha = R_{jkh}^i \xi_i^\alpha \xi_\beta^j \xi_c^k \xi_d^h, \\ P_{(\beta)c(\sigma)}^\alpha &= P_{\beta c(\sigma)}^\alpha = P_{jkh}^i \xi_i^\alpha \xi_\beta^j \xi_c^k \xi_\sigma^h, \\ S_{(\beta)^{(\gamma)(\sigma)}}^\alpha &= S_{\beta^{(\gamma)\sigma}}^\alpha = \widetilde{S}_{jkh}^i \xi_i^\alpha \xi_\beta^j \xi_\gamma^k \xi_\sigma^h, \\ \widetilde{S}_{jkh}^i &= S_{jkh}^i + h_{jk} h_h^i + h_{jh} h_k^i. \end{aligned}$$

Now, if we denote by " $R_{jkh}^i$  and ' $P_{jkh}^i$  the semi-indicatrized tensor



of  $R_{jkh}^i$  and the indicatrized tensor of  $P_{jkh}^i$ , then we have

$$(3.5) \quad \begin{aligned} {}^n R_{jkh}^i &= R_{jkh}^i + R_{jkh} l^i - R_{kh}^i l_j, \\ {}^p P_{jkh}^i &= P_{jkh}^i + P_{jkh} l^i - P_{kh}^i l_j, \quad P_{jkh} = g_{ij} P^i_{kh}, \end{aligned}$$

(I) The  $K_o$ -connection. From (2.2) we have

$$(3.6) \quad Q_n^a = Q_b^n = Q_b^{(a)} = Q_{(b)}^a = O.$$

Then, from (3.2), (3.4), (3.5) and (3.6) we have

$$(3.7)_1 \quad \begin{aligned} R_{bcd}^a &= {}^n R_{jkh}^i \xi_i^a \xi_b^j \xi_c^k \xi_d^h, \quad P_{bc(\sigma)}^a = {}^p P_{jkh}^i \xi_i^a \xi_b^j \xi_c^k \xi_\sigma^h, \\ S_{b(\gamma)(\sigma)}^a &= \widetilde{S}_{jkh}^i \xi_i^a \xi_b^j \xi_\gamma^k \xi_\sigma^h, \end{aligned}$$

$$(3.7)_2 \quad R_{(\beta)cd}^a = P_{(\beta)c(\sigma)}^a = S_{(\beta)(\gamma)(\sigma)}^a = O,$$

$$(3.7)_3 \quad R_b^{(\alpha)cd} = P_b^{(\alpha)c(\sigma)} = S_b^{(\alpha)(\gamma)(\sigma)} = O,$$

$$(3.7)_4 \quad \begin{aligned} R_{(\beta)cd}^{(\alpha)} &= {}^n R_{jkh}^i \xi_i^\alpha \xi_\beta^j \xi_c^k \xi_d^h, \quad P_{(\beta)c(\sigma)}^{(\alpha)} = {}^p P_{jkh}^i \xi_i^\alpha \xi_\beta^j \xi_c^k \xi_\sigma^h, \\ S_{(\beta)(\gamma)(\sigma)}^{(\alpha)} &= \widetilde{S}_{jkh}^i \xi_i^\alpha \xi_\beta^j \xi_\gamma^k \xi_\sigma^h. \end{aligned}$$

As well known, any indicatrix of  $M$  is locally flat if and only if  $\widetilde{S}_{jkh}^i = O$ . It follows from (3.7)<sub>1</sub> and (3.7)<sub>4</sub> that  $K_{BCD}^A = O$  if and only if  ${}^n R_{jkh}^i = {}^p P_{jkh}^i = \widetilde{S}_{jkh}^i = O$ .

(II) The  $K$ -connection. The curvature tensor with respect to this connection is already known as follows ([6], [9], [13]):

$$(3.8)_1 \quad \begin{aligned} R_{bcd}^a &= R_{jkh}^i \xi_i^a \xi_b^j \xi_c^k \xi_d^h, \quad P_{bc(\sigma)}^a = P_{jkh}^i \xi_i^a \xi_b^j \xi_c^k \xi_\sigma^h, \\ S_{b(\gamma)(\sigma)}^a &= S_{jkh}^i \xi_i^a \xi_b^j \xi_\gamma^k \xi_\sigma^h, \end{aligned}$$

$$(3.8)_2 \quad R_{(\beta)cd}^a = P_{(\beta)c(\sigma)}^a = S_{(\beta)(\gamma)(\sigma)}^a = O,$$

$$(3.8)_3 \quad R_b^{(\alpha)cd} = P_b^{(\alpha)c(\sigma)} = S_b^{(\alpha)(\gamma)(\sigma)} = O,$$

$$(3.8)_4 \quad \begin{aligned} R_{(\beta)cd}^{(\alpha)} &= {}^n R_{jkh}^i \xi_i^\alpha \xi_\beta^j \xi_c^k \xi_d^h, \quad P_{(\beta)c(\sigma)}^{(\alpha)} = {}^p P_{jkh}^i \xi_i^\alpha \xi_\beta^j \xi_c^k \xi_\sigma^h, \\ S_{(\beta)(\gamma)(\sigma)}^{(\alpha)} &= \widetilde{S}_{jkh}^i \xi_i^\alpha \xi_\beta^j \xi_\gamma^k \xi_\sigma^h. \end{aligned}$$

Suppose  $K_{BCD}^A = O$ . Then from (3.8)<sub>1</sub> and (3.8)<sub>4</sub>, we have  $h_{jk} h^i_k$

$-h_{jh}h^i_k = 0$ , contraction of which by  $g^{ih}$  yields  $(n-2)h_{jk} = 0$ . So we have  $n=2$  or  $h_{jk} = 0$ . A Finsler space  $M$  is called *quasi-locally Minkowskian* [14] if  $R^i_{jkh} = P^i_{jkh} = 0$ . If  $n=2$ , we have always  $S^i_{jkh} = \tilde{S}^i_{jkh} = 0$ . Therefore,  $K^A_{BCD} = 0$  if and only if  $R^i_{jkh} = P^i_{jkh} = 0$ .

Summarizing the results obtained, we have

**Theorem 1.** *The curvature tensor  $K^A_{BCD}$  with respect to the  $K_o$ -connection is given by (3.7)<sub>1</sub>~(3.7)<sub>4</sub>. In this case,  $K^A_{BCD} = 0$  if and only if any indicatrix of  $M$  is locally flat and  ${}^{\prime}R^i_{jkh} = {}^{\prime}P^i_{jkh} = 0$ . For the  $K$ -connection, the following hold good:*

(i) *When  $n=2$ , the curvature tensor  $K^A_{BCD}$  vanishes if and only if  $M$  is quasi-locally Minkowskian.*

(ii) *When  $n \geq 3$ , the curvature tensor  $K^A_{BCD}$  never vanishes.*

(III) **The D-connection.** Because of (3.1)~(3.3) we can express as

$$(3.9) \quad \begin{aligned} \bar{\Omega}_b^a &= (\omega_b^c \wedge \omega_c^a - d\omega_b^a) + \omega_b^{(\gamma)} \wedge \omega_{(\gamma)}^a = \Omega_b^a + \sum \omega_a^{(\varepsilon)} \wedge \omega_b^{(\varepsilon)} \\ &= \frac{1}{2} \bar{R}^a_{bcd} \omega^c \wedge \omega^d + \bar{P}^a_{bc(\sigma)} \omega^c \wedge \omega^{(\sigma)} + \frac{1}{2} \bar{S}^a_{b(\gamma)(\sigma)} \omega^{(\gamma)} \wedge \omega^{(\sigma)}. \end{aligned}$$

Therefore if we put

$$(3.10)_1 \quad \begin{aligned} \bar{R}^a_{bcd} &= \dot{R}^i_{jikh} \zeta_b^j \zeta_c^i \zeta^k \zeta^h, \quad \bar{P}^a_{bc(\sigma)} = \dot{P}^i_{jikh} \zeta_b^j \zeta_c^i \zeta^k \zeta^h, \\ \bar{S}^a_{b(\gamma)(\sigma)} &= \dot{S}^i_{jikh} \zeta_b^j \zeta_c^i \zeta^k \zeta^h, \end{aligned}$$

then from (2.4), (3.3) and (3.9) we have

$$(3.10)_{1'} \quad \begin{aligned} \dot{R}^i_{jikh} &= R^i_{jikh} + B_{rjh} B^r_{ik} - B_{rjk} B^r_{jh}, \\ \dot{P}^i_{jikh} &= P^i_{jikh} + P_{rjh} B^r_{ik} - B_{rjk} P^r_{ih}, \\ \dot{S}^i_{jikh} &= S^i_{jikh} + P_{rjh} P^r_{ik} - P_{rjk} P^r_{ih}. \end{aligned}$$

For  $\bar{\Omega}_{(\beta)}^a$ , we have

$$(3.11) \quad \begin{aligned} \bar{\Omega}_{(\beta)}^a &= d\omega_{(\beta)}^a + \sum \omega_c^a \wedge \omega_c^{(\beta)} + \sum \omega_a^{(\gamma)} \wedge \omega_{(\beta)}^{(\gamma)} \\ &= \frac{1}{2} \bar{R}_{(\beta)cda} \omega^c \wedge \omega^d + \bar{P}_{(\beta)c(\sigma)} \omega^c \wedge \omega^{(\sigma)} + \frac{1}{2} \bar{S}_{(\beta)(\gamma)(\sigma)} \omega^{(\gamma)} \wedge \omega^{(\sigma)}, \end{aligned}$$

$$(3.10)_2 \quad \begin{aligned} \bar{R}_{(\beta)cda} &= \dot{R}^i_{jikh} \zeta_{(\beta)}^j \zeta_c^i \zeta^k \zeta^h, \quad \bar{P}_{(\beta)c(\sigma)} = \dot{P}^i_{jikh} \zeta_{(\beta)}^j \zeta_c^i \zeta^k \zeta^h, \\ \bar{S}_{(\beta)(\gamma)(\sigma)} &= \dot{S}^i_{jikh} \zeta_{(\beta)}^j \zeta_c^i \zeta^k \zeta^h. \end{aligned}$$

After a long calculation using (1.14), (1.15), (1.17), (2.4), (3.11) and the Bianchi's identities, we have

$$\begin{aligned}
 \overset{2}{R}_{jikh} &= \bar{B}_{jik|h} - B_{jih|k} - P_{jir} R^r_{hk}, \\
 (3.10)_{2'} \quad \overset{2}{P}_{jikh} &= B_{jik|h} - P_{j(h|k} + B_{hik} l_j + B_{jir} A^r_{kh} + P_{jir} P^r_{kh}, \\
 \overset{2}{S}_{jikh} &= P_{hjk} - P_{kjh} + P_{jih} l_k - P_{jik} l_h - P_{jkr} A^r_{ih} + P_{jhr} A^r_{ik}.
 \end{aligned}$$

For  $\bar{Q}_b^{(a)}$ , we have

$$\begin{aligned}
 \bar{Q}_b^{(a)} &= -Q_b^{(a)} = \frac{1}{2} \bar{R}_b^{(a)}{}_{cd} \omega^c \wedge \omega^d + \bar{P}_b^{(a)}{}_{c(\sigma)} \omega^c \wedge \omega^{(\sigma)} \\
 &\quad + \frac{1}{2} \bar{S}_b^{(a)}{}_{(\gamma)(\sigma)} \omega^{(\gamma)} \wedge \omega^{(\sigma)}, \\
 (3.10)_3 \quad \bar{R}_b^{(a)}{}_{cd} &= \overset{3}{R}{}^i{}_{jkh} \xi_i^a \xi_j^c \xi_k^c \xi_h^d, \quad \bar{P}_b^{(a)}{}_{c(\sigma)} = \overset{3}{P}{}^i{}_{jkh} \xi_i^a \xi_j^c \xi_k^c \xi_h^\sigma, \\
 \bar{S}_b^{(a)}{}_{(\gamma)(\sigma)} &= \overset{3}{S}{}^i{}_{jkh} \xi_i^a \xi_j^c \xi_k^c \xi_h^\sigma, \\
 \overset{3}{R}{}^i{}_{jkh} &= B^i{}_{jk|h} - B^i{}_{jh|k} - P^i{}_{jr} R^r_{kh}, \\
 (3.10)_{3'} \quad \overset{3}{P}{}^i{}_{jkh} &= P^i{}_{jh|k} - B^i{}_{jk|h} - B_{hjk} l^i - B^i{}_{jr} A^r_{kh} - P^i{}_{jr} P^r_{kh}, \\
 \overset{3}{S}{}^i{}_{jkh} &= P^i{}_{kjh} - P^i{}_{hjk} - P^i{}_{jh} l_k + P^i{}_{jk} l_h - P^i{}_{hr} A^r_{jk} + P^i{}_{kr} A^r_{jh}.
 \end{aligned}$$

For  $\bar{Q}_{\beta}^{(\alpha)}$ , we have

$$\begin{aligned}
 \bar{Q}_{\beta}^{(\alpha)} &= Q_{\beta}^{(\alpha)} + \sum_c \omega_c^{(\alpha)} \wedge \omega_c^{(\beta)} \\
 (3.12) \quad &= \frac{1}{2} \bar{R}_{(\beta)cd}^{(\alpha)} \omega^c \wedge \omega^d + \bar{P}_{(\beta)c(\sigma)}^{(\alpha)} \omega^c \wedge \omega^{(\sigma)} \\
 &\quad + \frac{1}{2} \bar{S}_{(\beta)(\gamma)(\sigma)}^{(\alpha)} \omega^{(\gamma)} \wedge \omega^{(\sigma)}, \\
 (3.10)_4 \quad \bar{R}_{(\beta)cd}^{(\alpha)} &= \overset{4}{R}{}^i{}_{jkh} \xi_i^{\alpha} \xi_j^c \xi_k^c \xi_h^d, \quad \bar{P}_{(\beta)c(\sigma)}^{(\alpha)} = \overset{4}{P}{}^i{}_{jkh} \xi_i^{\alpha} \xi_j^c \xi_k^c \xi_h^\sigma, \\
 \bar{S}_{(\beta)(\gamma)(\sigma)}^{(\alpha)} &= \overset{4}{S}{}^i{}_{jkh} \xi_i^{\alpha} \xi_j^c \xi_k^c \xi_h^\sigma.
 \end{aligned}$$

From (2.4), (3.4), (3.5) and (3.12) we obtain

$$\begin{aligned}
 \overset{4}{R}{}^i{}_{jkh} &= {}^r R^i{}_{jkh} + (B^i{}_{sk} B_{jth} - B^i{}_{sh} B_{jtk}) g^{st}, \\
 (3.10)_{4'} \quad \overset{4}{P}{}^i{}_{jkh} &= {}^r P^i{}_{jkh} + (B^i{}_{sk} P_{jth} - P^i{}_{sh} B_{jtk}) g^{st}, \\
 \overset{4}{S}{}^i{}_{jkh} &= \widetilde{S}^i{}_{jkh} + P^i{}_{rk} P^r_{jh} - P^i{}_{rh} P^r_{jk}.
 \end{aligned}$$

Especially if  $\overset{4}{S}_{jikh} = \overset{4}{S}_{jihk} = 0$ , then we have  $(n-2) h_{jk} = 0$ . Therefore when  $n \geq 3$ , the tensor  $K^A_{BCD}$  never vanishes.

(IV) The  $D_0$ -connection. In the same way as before we can express as



$$\bar{Q}_b^a = \frac{1}{2} \bar{R}_{bcd}^a \omega^c \wedge \omega^d + \bar{P}_{bc(\sigma)}^a \omega^c \wedge \omega^{(\sigma)} + \frac{1}{2} \bar{S}_{b(\gamma)(\sigma)}^a \omega^{(\gamma)} \wedge \omega^{(\sigma)},$$

and put

$$(3.11)_1 \quad \begin{aligned} \bar{R}_{bcd}^a &= \overset{(1)}{R}_{jkh}^i \xi_i^a \xi_b^j \xi_c^k \xi_d^h, \quad \bar{P}_{bc(\sigma)}^a = \overset{(1)}{P}_{jkh}^i \xi_i^a \xi_b^j \xi_c^k \xi_\sigma^h, \\ \bar{S}_{b(\gamma)(\sigma)}^a &= \overset{(1)}{S}_{jkh}^i \xi_i^a \xi_b^j \xi_\gamma^k \xi_\sigma^h. \end{aligned}$$

In this case, since the relation between the  $D_o$ - and  $D$ -connections is the same as that between the  $K_o$ - and  $K$ -connections, we have

$$(3.11)_1' \quad \begin{aligned} \overset{(1)}{R}_{jih} &= {}^oR_{jih} + B_{rjh} B^r{}_{ik} - B_{rjk} B^r{}_{ih}, \\ \overset{(1)}{P}_{jih} &= {}^oP_{jih} + P_{rjh} B^r{}_{ik} - B_{rjk} P^r{}_{ih}, \\ \overset{(1)}{S}_{jih} &= \overset{\sim}{S}_{jih} + P_{rjh} P^r{}_{ik} - P_{rjk} P^r{}_{ih}. \end{aligned}$$

For  $\bar{Q}_{(\beta)}^a$ , we have

$$(3.11)_2 \quad \begin{aligned} \bar{Q}_{(\beta)}^a &= \bar{Q}_{(\beta)}^a - \omega_n^a \wedge \omega_n^{(\beta)} = \bar{Q}_{(\beta)}^a - (h_h^i R_{jok}) \xi_i^a \xi_\beta^j \xi_c^k \xi_\sigma^h \omega^c \wedge \omega^{(\sigma)} \\ &= \frac{1}{2} \bar{R}_{(\beta)cd}^a \omega^c \wedge \omega^d + \bar{P}_{(\beta)c(\sigma)}^a \omega^c \wedge \omega^{(\sigma)} + \bar{S}_{(\beta)(\gamma)(\sigma)}^a \omega^{(\gamma)} \wedge \omega^{(\sigma)}, \\ \bar{R}_{(\beta)cd}^a &= \overset{(2)}{R}_{jih}^i \xi_\beta^j \xi_c^i \xi_d^k \xi_h^h, \quad \bar{P}_{(\beta)c(\sigma)}^a = \overset{(2)}{P}_{jih}^i \xi_\beta^j \xi_c^i \xi_\sigma^k \xi_h^h, \\ \bar{S}_{(\beta)(\gamma)(\sigma)}^a &= \overset{(2)}{S}_{jih}^i \xi_\beta^j \xi_\gamma^i \xi_\sigma^k \xi_h^h, \end{aligned}$$

$$(3.11)_2' \quad \overset{(2)}{R}_{jih} = \overset{2}{R}_{jih}, \quad \overset{(2)}{P}_{jih} = \overset{2}{P}_{jih} + h_{ih} R_{jok}, \quad \overset{(2)}{S}_{jih} = \overset{2}{S}_{jih}.$$

For  $\bar{Q}_b^{(\alpha)}$ , we have

$$(3.11)_3 \quad \begin{aligned} \bar{R}_b^{(\alpha)cd} &= \overset{(3)}{R}_{jih}^i \xi_b^\alpha \xi_c^j \xi_d^k \xi_h^h, \quad \bar{P}_b^{(\alpha)c(\sigma)} = \overset{(3)}{P}_{jih}^i \xi_b^\alpha \xi_c^j \xi_\sigma^k \xi_h^h, \\ \bar{S}_b^{(\alpha)(\gamma)(\sigma)} &= \overset{(3)}{S}_{jih}^i \xi_b^\alpha \xi_\gamma^j \xi_\sigma^k \xi_h^h, \end{aligned}$$

$$(3.11)_3' \quad \overset{(3)}{R}_{jih} = \overset{3}{R}_{jih}, \quad \overset{(3)}{P}_{jih} = \overset{3}{P}_{jih} + h_{jh} R^i{}_{ok}, \quad \overset{(3)}{S}_{jih} = \overset{3}{S}_{jih}.$$

For  $\bar{Q}_{\{\beta\}}$ , we have

$$(3.11)_4 \quad \bar{S}_{\{\beta\}(\gamma)(\sigma)}^{(\alpha)} = \overset{(4)}{S}_{jih}^i \xi_i^\alpha \xi_\beta^j \xi_\gamma^k \xi_\sigma^h,$$

$$(3.11)_4' \quad \overset{(4)}{R}_{jih} = \overset{4}{R}_{jih}, \quad \overset{(4)}{P}_{jih} = \overset{4}{P}_{jih}, \quad \overset{(4)}{S}_{jih} = \overset{4}{S}_{jih}.$$

Thus we have

**Theorem 2.** *The curvature tensor  $K_{bcd}^a$  with respect to the  $D$ -connection is given by (3.10)<sub>1</sub>, (3.10)<sub>1'</sub> ~ (3.10)<sub>4</sub>, (3.10)<sub>4'</sub>. Especially*

when  $n \geq 3$ , the tensor  $K_{BCD}^A$  never vanishes. The curvature tensor  $K_{BCD}^A$  with respect to the  $D_\sigma$ -connection is given by (3.11)<sub>1</sub>, (3.11)<sub>1'</sub> ~ (3.11)<sub>4</sub>, (3.11)<sub>4'</sub>.

§ 4. Special cases. In the previous section we have introduced many new tensors on  $M$ . However, for the present, we can not explicate the geometrical meanings of these tensors. In this section, therefore, we shall try it for special Finsler spaces.

(A) Let  $M$  be a space with absolute parallelism of line-elements, that is,  $R_{jk}^i = 0$ . Then for the  $D$ -connection, we have

$$\begin{aligned}
 \overset{1}{R}_{jikh} &= \overset{4}{R}_{jikh} = R_{jikh} + S_{jikh}, \\
 \overset{1}{P}_{jikh} &= P_{jikh} + P_{rjh} A^r_{ik} - A_{rjk} P^r_{ih}, \\
 \overset{1}{S}_{jikh} &= S_{jikh} + P_{rjh} P^r_{jk} - P_{rjk} P^r_{ih}, \\
 \overset{2}{R}_{jikh} &= \overset{2}{R}_{ijkh} = -\overset{3}{R}_{ijkh} = -\overset{3}{R}_{jikh} = +A_{jik|h} - A_{jih|k}, \\
 (4.1) \quad \overset{2}{P}_{jikh} &= -\overset{3}{P}_{ijkh} = +A_{jik|h} - P_{jih|k} + A_{hik} l_j + A_{jir} A^r_{kh} + P_{jir} P^r_{kh}, \\
 \overset{2}{S}_{jikh} &= \overset{2}{S}_{ijkh} = -\overset{3}{S}_{ijkh} = -\overset{3}{S}_{jikh} = +P_{hjik} - P_{kjih} \\
 &\quad - P_{jkr} A^r_{ih} + P_{jhr} A^r_{ik} - P_{jik} l_h + P_{jih} l_k, \\
 \overset{4}{P}_{jikh} &= \overset{1}{P}_{jikh} + A_{rjh} P^r_{ik} - A_{rjk} P^r_{ih}, \\
 \overset{4}{S}_{jikh} &= \overset{1}{S}_{jikh} + P_{rjh} P^r_{ik} - P_{rjk} P^r_{ih}
 \end{aligned}$$

Then we have

**Theorem 3.** Let  $M$  be a space with absolute parallelism of line-elements. Then the curvature tensor  $K_{BCD}^A$  with respect to the  $D$ -connection is determined by (4.1). In this case, the following propositions hold good:

- (1)  $M$  is quasi-locally Minkowskian if and only if  $\overset{1}{P}_{jikh} = 0$  or  $\overset{2}{R}_{jikh} = 0$ .
- (2)  $M$  is locally Euclidean if and only if  $\overset{2}{P}_{jikh} = 0$  and  $(\overset{1}{P}_{jikh} = 0$  or  $\overset{2}{R}_{jikh} = 0)$ .
- (3) When  $n = 2$ , the curvature tensor  $K_{BCD}^A$  vanishes if and only if  $M$  is locally Euclidean.

Proof. Firstly, we shall prove the proposition (1). Contracting  $\overset{1}{P}_{jikh} = 0$  by  $l^j$ , we have  $P_{ikh} = 0$ . We know that  $P_{ijk} = R_{ijk} = 0$  is equi-

valent to  $P_{Jikh} = R_{Jikh} = 0$ . Next, it is well known that  $P_{ijk} = 0$  is equivalent to  $\overset{2}{R}_{Jikh} = A_{jih|k} - A_{jik|h} = 0$ .

Secondly, we prove the proposition (2). Suppose  $P_{ijk} = 0$ . Then from  $\overset{2}{P}_{Jikh} = 0$ , we obtain

$$(4.2) \quad A_{jik|h} = -l_j A_{ikh} - A_{jir} A^r_{kh}.$$

Since the right hand side of (4.2) is symmetric in the indices  $k$  and  $h$ , we have  $A_{jik|h} - A_{jih|k} = 0$ , contraction of which by  $l^k$  yields  $A_{jih} = 0$ , that is,  $M$  is Riemannian. Accordingly  $R^i_{hjk}$  are functions of  $x$  alone. Then, differentiating  $R^i_{hjk} y^h = 0$  by  $y^h$ , we have  $R^i_{hjk} = 0$ .

Lastly, we prove the proposition (3). If  $M$  is of dimension 2, then we have always  $S_{jikh} = \widetilde{S}_{jikh} = 0$ . If  $K^A_{BCD} = 0$ , it follows from the proposition (2) that  $M$  is locally Euclidean. The converse is clear. Q. E. D.

For the  $D_0$ -connection, we have

$$(4.3) \quad \begin{aligned} \overset{(1)}{R}_{Jikh} &= \overset{(4)}{R}_{Jikh} = \overset{1}{R}_{Jikh}, & \overset{(1)}{P}_{Jikh} &= \overset{(4)}{P}_{Jikh} = \overset{4}{P}_{Jikh}, \\ \overset{(1)}{S}_{jikh} &= \overset{(4)}{S}_{jikh} = \overset{4}{S}_{jikh}, & \overset{(2)}{R}_{jikh} &= -\overset{(3)}{R}_{jikh} = \overset{2}{R}_{jikh}, \\ \overset{(2)}{P}_{jikh} &= -\overset{(3)}{P}_{jikh} = \overset{2}{P}_{jikh}, & \overset{(2)}{S}_{jikh} &= -\overset{(3)}{S}_{jikh} = \overset{2}{S}_{jikh}. \end{aligned}$$

Hence we have

**Corollary 3.1.** *Let  $M$  be a space with absolute parallelism of line-elements. Then the curvature tensor  $K^A_{BCD}$  with respect to the  $D_0$ -connection is determined by only the components  $\overset{1}{R}_{jikh}$ ,  $\overset{2}{R}_{jikh}$ ,  $\overset{2}{P}_{jikh}$ ,  $\overset{2}{S}_{jikh}$ ,  $\overset{4}{P}_{jikh}$  and  $\overset{4}{S}_{jikh}$  of the curvature tensor with respect to the  $D$ -connection. And the following propositions hold good still:*

- (1)  $M$  is quasi-locally Minkowskian if and only if  $\overset{(2)}{R}_{Jikh} = 0$ .
- (2)  $M$  is locally Euclidean if and only if  $\overset{(2)}{R}_{jikh} = \overset{(2)}{P}_{jikh} = 0$ .
- (3) When  $n = 2$ , the curvature tensor  $K^A_{BCD}$  vanishes if and only if  $M$  is locally Euclidean.

(B) Let  $M$  be a Landsberg space, that is,  $P^i_{jk} = 0$ . Then for the  $D$ -connection, we have

$$\overset{1}{P}_{jikh} = \overset{2}{S}_{jikh} = \overset{3}{S}_{jikh} = \overset{4}{P}_{jikh} = 0, \quad \overset{1}{S}_{jikh} = S_{jikh},$$



$$\begin{aligned}
 (4.4) \quad & \overset{1}{R}_{jikh} = P_{jikh} + B_{rjh} B^r{}_{ik} - B_{rjk} B^r{}_{ih}, \quad \overset{4}{S}_{jikh} = \widetilde{S}_{jikh}, \\
 & \overset{2}{R}_{jikh} = -\overset{3}{R}_{ljkh} = +R_{jik|h} - R_{jih|k} \\
 & \overset{2}{P}_{jikh} = -\overset{3}{P}_{ijkh} = B_{jik|h} + B_{hik} l_j + B_{jir} A^r{}_{kh}, \\
 & \overset{4}{R}_{jikh} = {}^n R_{jikh} + (B_{isk} B_{jth} - B_{ish} B_{jtk}) g^{st}.
 \end{aligned}$$

Then we can state

**Theorem 4.** *Let  $M$  be a Landsberg space. Then the curvature tensor  $K_{BCD}^A$  with respect to the  $D$ -connection is determined by (4.4). In this case, the following propositions hold good:*

(1) *The tensor  $R_{ijk}$  is  $h$ -covariant constant on  $M$  if and only if  $\overset{2}{R}_{jikh} = 0$ .*

(2) *When  $n \geq 3$ ,  $M$  is locally Euclidean if and only if  $\overset{2}{P}_{jikh} = 0$ .*

*When  $n = 2$ ,  $M$  is a Riemannian space if and only if  $\overset{2}{P}_{jikh} = 0$ .*

(3) *If  $M$  is of scalar curvature and  $\overset{1}{R}_{jikh} = 0$ , then  $M$  is a quasi-locally Minkowski space with  $S_{jikh} = 0$  or  $M$  is a Riemannian space of dimension 2 or  $M$  is locally Euclidean.*

(4) *If  $M$  is of constant curvature and  $\overset{4}{R}_{jikh} = 0$ , then  $M$  is a quasi-locally Minkowski space with  $S_{jikh} = 0$  or  $M$  is a two-dimensional Riemannian space of constant curvature or  $M$  is a Riemannian space of constant curvature 1.*

*Proof.* Firstly we prove the proposition (1). In a Landsberg space, a Bianchi's identity  $R_{jik|h} + R_{jih|k} + R_{jkh|i} = 0$  holds. From this identity and  $\overset{2}{R}_{jikh} = R_{jik|h} - R_{jih|k} = 0$ , we have  $R_{jkh|i} = 0$ .

Secondly, let us prove the proposition (2). We have another identity

$$(4.5) \quad R_{jik|h} + R_{jik} l_h - R_{hjik} + R_{jir} A^r{}_{kh} + R_{jrk} A^r{}_{ih} = 0.$$

Suppose  $\overset{2}{P}_{jikh} = 0$ , that is,

$$(4.6) \quad B_{jik|h} + B_{hik} l_j + B_{jir} A^r{}_{kh} = 0.$$

Then subtracting (4.5) from (4.6), we have

$$\begin{aligned}
 (4.7) \quad & A_{jik|h} + A_{jir} A^r{}_{kh} + R_{hjik} - R_{jik} l_h + R_{hik} l_j \\
 & + A_{hik} l_j + R_{jkr} A^r{}_{ih} = 0.
 \end{aligned}$$

Since  $A_{jik}|_h + A_{jit}A^r_{kh}$  is symmetric in the indices  $j$  and  $i$ , from (4.7) we have

$$\begin{aligned} R_{hjik} - R_{jik}l_h + R_{hik}l_j + A_{hik}l_j + R_{jkr}A^r_{jh} \\ = R_{hijk} - R_{ijk}l_h + R_{hjk}l_i + A_{hjk}l_i + R_{ikr}A^r_{jh}, \end{aligned}$$

contraction of which by  $l^j$  yields

$$(4.8) \quad A_{hik} = R_{hiok} - R_{iok}l_h + R_{hok}l_i.$$

The left hand side of (4.8) is symmetric in the indices  $h$  and  $i$ , while the right hand side is skew-symmetric in the same indices. Therefore we have  $A_{hik} = 0$  and hence from (4.7)

$$(4.9) \quad R_{hjik} = R_{jik}l_h - R_{hik}l_j,$$

which implies

$$(4.10) \quad F^2 R_{hjik} = R_{sjik}y^s g_{ht}y^t - R_{shik}y^s g_{it}y^t.$$

Differentiating (4.10) by  $y^p$  and  $y^q$  two times, contracting the resulting expression by  $g^{qs}$  and summing the result with respect to  $s$  and  $p$ , we obtain  $(n-2)R_{hjik} = 0$  i. e.  $R_{hjik} = 0$  or  $n = 2$ . Conversely if  $A_{ijk} = 0$  and  $R_{hjik} = 0$ , then  $\overset{2}{P}_{jikh} = 0$ . When  $n = 2$ , the relation (4.9) always holds. Therefore if  $A_{ijk} = 0$ , then from (4.5) and (4.9) we have  $\overset{2}{P}_{jikh} = R_{jik}|_h + R_{hik}l_j = 0$ .

Thirdly, we prove the proposition (3). From  $\overset{1}{R}_{jikh} = 0$ , we have

$$\begin{aligned} (4.11) \quad R_{jikh} + S_{jikh} + A_{rjh}A^r_{ik} - A_{rjk}R^r_{ih} + R_{rjh}A^r_{ik} - R_{rjk}A^r_{ih} \\ + R_{rjh}R^r_{ik} - R_{rjk}R^r_{ih} = 0, \end{aligned}$$

contraction of which by  $l^j$  yields

$$(4.12) \quad R_{ikh} + R_{roh}A^r_{ik} - R_{rok}A^r_{ih} + R_{roh}R^r_{ik} - R_{rok}R^r_{ih} = 0.$$

Further contracting (4.12) by  $l^k$ , we have

$$(4.13) \quad R_{ioh} = R_{roh}R^r_{oi}.$$

Let  $M$  be of scalar curvature  $R$ , that is,

$$(4.14) \quad R_{ioh} = R(x, y) h_{ih},$$

where  $R(x, y)$  is a homogeneous function of degree  $O$  in  $y^i$ . If we substitute (4.14) in (4.13), we get  $R(R-1)h_{ih} = 0$ , i. e.  $R=0$  or  $R=1$ . If  $R=0$ , then from (4.12) and (4.13) we have  $R_{ikh} = 0$  and hence  $R_{jikh} = 0$ . Therefore (4.11) leads us to  $S_{jikh} = 0$ .

Next, suppose  $R=1$ . Then we can express  $R_{ikh}$  as

$$(4.15) \quad R_{ikh} = l_k g_{ih} - l_h g_{ik}.$$

Substituting (4.15) in (4.11), we have

$$(4.16) \quad R_{jikh} = l_j R_{ikh} - l_i R_{jkh} - S_{jikh}.$$

Again if we substitute (4.15) and (4.16) in (4.5), then we get

$$h_{ih} g_{ik} - h_{kh} g_{ji} + l_i R_{hik} + S_{hjik} + l_i A_{jkh} - l_k A_{jih} = 0,$$

contraction of which by  $l^i$  gives  $A_{jkh} = 0$ . The sequent proof is the same as in the proposition (2).

Lastly we prove the proposition (4). From  $\overset{4}{R}_{jikh} = 0$ , we have

$$(4.17) \quad R_{jikh} - l_j R_{ikh} + l_i R_{jkh} + S_{jikh} + (A_{isk} R_{jth} - A_{ish} R_{jtk} \\ + R_{isk} A_{jth} - R_{ish} A_{jtk} + R_{isk} R_{jth} - R_{ish} R_{jtk}) g^{st} = 0.$$

Let  $M$  be of constant curvature, i. e.

$$(4.18) \quad R_{ijk} = R(l_j g_{ik} - l_k g_{ij}), \text{ where } R \text{ is constant.}$$

Substituting (4.18) in (4.5) and (4.17), we have

$$(4.19) \quad R_{jikh} = l_j R_{ikh} + R(h_{jk} g_{ih} - h_{jh} g_{ik} + l_k A_{ihj} - l_h A_{ikj}),$$

$$(4.20) \quad R_{jikh} + S_{jikh} - l_j R_{ikh} + l_i R_{jkh} + R(l_h R_{jik} - l_k R_{jih}) \\ + R^2(h_{jh} g_{ik} - h_{jk} g_{ih}) = 0.$$

Again, substitution of (4.19) in (4.20) yields

$$(4.21) \quad S_{jikh} + l_i R_{jikh} + R(h_{jk} g_{ih} - h_{jh} g_{ik} + l_h R_{jik} - l_k R_{jih} \\ + l_k A_{ijh} - l_h A_{ijk}) + R^2(h_{jh} g_{ik} - h_{jk} g_{ih}) = 0,$$



contraction of which by  $l^k$  gives  $RA_{jih} = 0$ , i. e.  $R = 0$  or  $A_{jih} = 0$ .

If  $R = 0$ , then we have  $R_{jikh} = S_{jikh} = 0$ . If  $A_{jih} = 0$ , then (4.21) leads us to  $R = 1$  or

$$(4.22) \quad h_{jh}g_{ik} - h_{jk}g_{ih} + l_i(l_h g_{jk} - l_k g_{jh}) = 0.$$

Contracting (4.22) by  $g^{ih}$ , we have  $(n - 2)h_{jk} = 0$ , i. e.  $n = 2$ . Q. E. D.

For the  $D_o$ -connection, we have

$$(4.22) \quad \begin{aligned} P_{jihk} &= S_{jihk} = S_{jikh} = P_{jikh} = 0, \quad S_{jihk} = S_{jikh} = \widetilde{S}_{jihk}, \\ R_{jihk} &= {}^{(1)}R_{jihk} + B_{rjh} B^r_{ik} - B_{rjk} B^r_{ih}, \quad R_{jikh} = -R_{ijkh} = {}^2R_{jikh}, \\ P_{jikh} &= -P_{ijkh} = B_{jik}|_h + B_{hik} l_j + B_{jlr} A^r_{kh} - h_{ih} R_{jok}, \\ R_{jikh} &({}^{(4)}R_{jikh} + (B_{isk} B_{jth} - B_{ish} B_{jtk}) g^{st}) = {}^4R_{jikh}. \end{aligned}$$

Then we have

**Corollary 4.4.** *Let  $M$  be a Landsberg space. Then the curvature tensor  $K^A_{BCD}$  with respect to the  $D_o$ -connection is determined by (4.22). In this case, the following propositions hold good:*

- (1) *The tensor  $R_{ijk}$  is  $h$ -covariant constant on  $M$  if and only if  $R_{jihk} = 0$*
- (2)  *$M$  is locally Euclidean if and only if  $R_{jihk} = 0$ .*
- (3) *If  $M$  is of scalar curvature and  $R_{jihk} = 0$ , the  $M$  is a quasi-locally Minkowski space with  $S_{jihk} = 0$ .*
- (4) *If  $M$  is of constant curvature and  $R_{jihk} = 0$ , then  $M$  is a quasi-locally Minkowski space with  $S_{jihk} = 0$  or  $M$  is a two-dimensional Riemannian space of constant curvature or  $M$  is a Riemannian space of constant curvature 1.*

*Proof.* The propositions (1) and (4) are the same as in Theorem 4. First, we prove the proposition (2). From  $P_{jihk} = 0$ , we have

$$(4.23) \quad B_{jik}|_h + B_{hik} l_j + B_{jlr} A^r_{kh} - h_{ih} R_{jok} = 0.$$

Then subtracting (4.5) from (4.23), we obtain

$$(4.24) \quad A_{jik}|_h + A_{jit} A^{\tau}_{kh} + R_{hjik} - R_{jik} l_h + R_{hik} l_j \\ + A_{hik} l_j + R_{jkt} A^{\tau}_{ih} - h_{ih} R_{jok} = 0.$$

In the same way as in Theorem 4, we have

$$(4.25) \quad A_{hik} = R_{hio\kappa} - R_{io\kappa} l_h + R_{hok} l_i = 0.$$

Therefore from (4.24) we get

$$(4.26) \quad R_{hjik} = R_{jik} l_h - R_{hik} l_j + h_{ih} R_{jok},$$

contraction of which by  $g^{ih}$  yields

$$(4.27) \quad R_{jk} = R_{ok} l_j + nR_{jok},$$

which implies

$$(4.28) \quad F^2 R_{jk} = R_{ik} y^i g_{jh} y_h + nR_{ijhk} y^i y^h.$$

Differentiating (4.28) by  $y^i$  and  $y^h$  two times, we have

$$(4.29) \quad 2g_{ih} R_{jk} = R_{ik} g_{jh} + R_{hk} g_{ij} + n(R_{ijhk} + R_{hjik}),$$

contraction of which by  $g^{ih}$  gives  $R_{jk} = 0$ . Then, from (4.27) and (4.29) we have

$$(4.30) \quad R_{jok} = 0, \quad R_{ijhk} + R_{hjik} = 0.$$

In the same way as before, we have  $R_{jikh} = 0$  or  $n = 2$ . When  $n = 2$ , the condition (4.30) implies  $R_{jikh} = 0$ , too.

Next, we prove the proposition (3). From  $R_{jikh}^{(1)} = 0$ , we obtain

$$(4.31) \quad R_{jikh} - l_j R_{ikh} + l_i R_{jkh} + S_{jikh} + A_{\tau jh} R^{\tau}_{ik} - A_{\tau jk} R^{\tau}_{ih} \\ + R_{\tau jh} A^{\tau}_{ik} - R_{\tau jk} A^{\tau}_{ih} + R_{\tau jh} R^{\tau}_{ik} - R_{\tau jk} R^{\tau}_{ih} = 0,$$

contraction of which by  $l^k$  yields

$$(4.32) \quad R_{jioh} - l_j R_{ioh} + l_i R_{joh} - A_{\tau jh} R^{\tau}_{oi} + R_{\tau oj} A^{\tau}_{ih} - R_{\tau jh} R^{\tau}_{oi} \\ + R_{\tau oj} R^{\tau}_{ih} = 0.$$

Further contracting (4.32) by  $l^i$ , we have

$$(4.33) \quad R_{\tau o h} R^{\tau o i} = O.$$

Let  $M$  be of scalar curvature. Then if we substitute (4.14) in (4.33), then we have  $R=O$  and hence  $R_{i o h} = O$ . Therefore by virtue of (4.32) we have  $R_{j i o h} = O$ , from which it follows that

$$(4.34) \quad R_{j i k h} = -R_{j i k s} |_h l^s.$$

On the other hand, the following identity holds good:

$$(4.35) \quad R_{j i k s} |_h + S_{j i s \tau} R^{\tau h k} - R_{j i s \tau} A^{\tau k h} + R_{j i k \tau} A^{\tau s h} = O.$$

In consequence of (4.34), (4.35) and  $R_{j i o h} = O$ , we have  $R_{j i k h} = O$ . Accordingly from (4.31) we obtain  $S_{j i k h} = O$ . Q. E. D.

(C) Let  $M$  be a quasi-locally Minkowski space, that is,  $P^i_{jk} = R^i_{jk} = O$ . Then for the  $D$ -connection, we obtain

$$(4.36) \quad \begin{aligned} \overset{1}{P}_{j i k h} &= \overset{2}{S}_{j i k h} = \overset{3}{S}_{j i k h} = \overset{2}{R}_{j i k h} = \overset{3}{R}_{j i k h} = \overset{4}{P}_{j i k h} = O, \\ \overset{1}{R}_{j i k h} &= \overset{4}{R}_{j i k h} = \overset{1}{S}_{j i k h} = S_{j i k h}, \quad \overset{4}{S}_{j i k h} = \widetilde{S}_{j i k h}, \\ \overset{2}{P}_{j i k h} &= -\overset{3}{P}_{i j k h} = A_{j i k} |_h + A_{h i k} l_j + A_{j i \tau} A^{\tau k h}. \end{aligned}$$

For the  $D_o$ -connection, we have

$$(4.37) \quad \begin{aligned} \overset{(1)}{P}_{j i k h} &= \overset{(2)}{S}_{j i k h} = \overset{(3)}{S}_{j i k h} = \overset{(2)}{R}_{j i k h} = \overset{(3)}{R}_{j i k h} = \overset{(4)}{P}_{j i k h} = O, \\ \overset{(1)}{R}_{j i k h} &= \overset{(4)}{R}_{j i k h} = S_{j i k h}, \quad \overset{(1)}{S}_{j i k h} = \overset{(4)}{S}_{j i k h} = \widetilde{S}_{j i k h}, \\ \overset{(2)}{P}_{j i k h} &= -\overset{(3)}{P}_{i j k h} = \overset{2}{P}_{j i k h}. \end{aligned}$$

Then we have

**Proposition 4.** *Let  $M$  be a quasi-locally Minkowski space. Then the curvature tensors with respect to the  $D_o$ - and  $D$ -connections are determined by (4.36) and (4.37) respectively.  $M$  is locally Euclidean if and only if  $\overset{2}{P}_{j i k h} = O$ .*

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